# Modeling molecular kinetics with deep learning

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Mardt et al., "VAMPnets for deep learning of molecular kinetics.", Nature communications 9.1 (2018): 5.

# Sampling Problem

- We want to learn the stationary distribution p(x) (gives access to all thermodynamic properties, conformation = one possible 3D structure) and kinetics
- Time step simulation [fs], interesting timescale [s]
- Instead of the stationary distribution learn the conditional distribution



 $p(x_{t+\tau}|x_t)$ 

Karplus et al., "Molecular dynamics and protein function". PNAS, 102.19 (2005): 6679-6685.

# Markov State Models

- Equilibrium simulation is not necessary → run short trajectories in parallel
- Learning  $p(x_{t+\tau}|x_t)$  by mapping into a state space + transition rates
- gives access to p(x) + kinetics



Plattner et al., "Complete proteinprotein association kinetics in atomic detail revealed by molecular dynamics simulations and Markov modelling". Nature chemistry, 9(10), 1005. (2017)

- Handcrafted modeling is prone to errors
- We propose a Neural Network framework to substitute the whole pipeline
- Entire mapping from molecular coordinates to coarse-grained model encoded in a neural network



## **Neural Network**



$$\hat{y} = f_2(\mathbf{W}_2 f_1(\mathbf{W}_1 x))$$

- Layers consist of Nodes, which are connected to the nodes of the subsequent layer
- Connections are weighted by trainable parameters  $\mathbf{W}_{\mathbf{i}}$
- Nodes apply nonlinear functions  $f_i$  to the sum of inputs
- Universal approximation theorem: 3-layered NNs can approximate any function

- Process of updating the parameters of the network
- Target of the update is the minimization of a given loss function L:
- 1. Initialize the weights  $\mathbf{W}_i$  and split data
- 2. Until stopping criterion is reached:
  - 2.1 For every batch of training samples  $x^{(i)}$ :
    - 2.1.1 Compute output value  $\hat{y}^{(i)}$
    - 2.1.2 Compute value of loss function  $L(\hat{y})$
    - 2.1.3 Compute  $abla_{\mathbf{W_i}}L$
    - 2.1.4 Update  $\mathbf{W_i}$
  - 2.2 Evaluate L on validation set
- 3. Evaluate L on test set

Given  $\chi: \mathbb{R}^n \to \mathbb{R}^m$ , we want to minimize the prediction error:

 $\mathbb{E}_t[\boldsymbol{\chi}(\mathbf{x}_{t+\tau})] \approx \mathbf{K}^T \mathbb{E}_t[\boldsymbol{\chi}(\mathbf{x}_t)]$ 

The optimal K is given by:

$$\begin{split} \mathbf{K} &= \mathbf{C}_{00}^{-1} \mathbf{C}_{01}, \text{ with} \\ \mathbf{C}_{00} &= \mathbb{E}_t [ \boldsymbol{\chi}(\mathbf{x}_t) \boldsymbol{\chi}(\mathbf{x}_t)^T ] \\ \mathbf{C}_{01} &= \mathbb{E}_t [ \boldsymbol{\chi}(\mathbf{x}_t) \boldsymbol{\chi}(\mathbf{x}_{t+\tau})^T ]. \end{split}$$

This leaves the choice of  $\chi$ . The following VAMP score is maximal if  $(\chi_1, ..., \chi_m)$  span the *m* dominant singular functions of the real  $\mathcal{K}$ :

$$\hat{R}_2 = ||\mathbf{C}_{00}^{-1/2}\mathbf{C}_{01}\mathbf{C}_{11}^{-1/2}||_F^2.$$

Wu, Noe, "Variational approach for learning Markov processes from time series data", 2017, arXiv:1707.04659

### VAMPnets

- NNs are used to represent  $\chi$
- Trained to maximize the VAMP-score



network lobe II



### VAMPnets

- Dimensionality reduction through the lower number of output nodes
- Coarse-graining is implemented through softmax output layers
- Output nodes=number of states, value is probability to belong in that state
- We can calculate the K matrix and test for dynamical processes



# **Example: Alanine Dipeptide**



## **Results: Alanine Dipeptide**



## **Results: Alanine Dipeptide**



### **Results: Alanine Dipeptide**

- VAMPnets with a 2-node bottleneck
- Network is forced to learn a 2D representation



# Villin



Have you installed *PyTorch*? If not, go to https://pytorch.org, scroll down to "Install PyTorch", choose your OS and platform "CPU". Copy the conda command to your terminal, where you have activated the workshop environment, and run it.